ABSTRACT

To improve the operation of robots in installations repro-
gramming and emptying an operating sequence to be performed
by them, the invention provides a method and a device for
visualizing computer-assisted information in an image of
the real environment on a viewing device, in which there is
a determination of the position and orientation or pose of
the image receiving device and that robot-specific informa-
tions corresponding to this determination are faded over
the image of the real environment on the viewing device.

LIST OF REFERENCE NUMERALS

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| 1 | Device |
| 1.1 | Viewing device |
| 1.2 | Camera |
| 1.3 | Spectacle lenses |
| 1.4 | Cable |
| 2 | Manual programmer |
| 2.1 | Movement keys |
| 2.2 | 6D mouse |
| 2.3 | Screen |
| 3 | Sensor system |
| 3.1 | Stationary receiving system |
| 3.2 | Input element |
| 4 | User |
| 4.1, 4.1' | Hand |
| 4.1a | Virtual hand |
| 5 | Processing unit |
| 5.1 | Image generating unit |
| 5.2 | Manipulating unit |
| 6 | Robot control |
| 7 | Robot |
| 7' | Further position |
| 7.1 - 7.3 | Cooperating robots |
| 7.1' - 7.3' | Operating area |
| 7a | Base |
| 7b | Hand flange |
| 8 | Workpiece |
| 8' | Simulated workpiece |
| P1-P6 | Path points |
| AO, AO' | Augmented space object |